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# **HYPERSENSPECTRAL TEXTURE ANALYSIS FOR COLON TISSUE BIOPSY CLASSIFICATION**

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## **ABSTRACT**

Diagnosis and cure of colon cancer can be improved by performing automated histopathological analysis of colon biopsy samples. Due to significant observational variation between pathologists in several histological features, there is a need for the development of automated, quantitative analysis techniques. This paper presents a promising automative technique for the classification of hyperspectral colon tissue biopsy images. The application of hyperspectral imaging techniques in medical image analysis is a new domain for researchers. The main advantage of using hyperspectral imaging is the increased spectral resolution and detailed subpixel information. The proposed classification algorithm is based on the subspace projection techniques particularly Support Vector Machines (SVM) with Gaussian Kernel. Dimensionality reduction and tissue segmentation is achieved by Independent Component Analysis (ICA) and  $k$ -means clustering. Morphological features, which describe the shape, orientation and other geometrical attributes, are extracted in first set of experiments. Grey level co-occurrence matrices are computed for the second set of experiments. The SVM with appropriate choice of parameters for its Gaussian kernel efficiently exploits the non linear boundary between the benign and malignant classes of the colon tissue biopsies.

## **1. INTRODUCTION**

Colon cancer is a malignant disease of the large bowel. After lung and breast cancer, colorectal cancer (a combined term for colon and rectal cancer) is the most common cause of death for cancers in the Western world. The incidence of disease in England and Wales is about 30,000 cases/year, resulting in approximately 17,000 death/annum [13], and it has been estimated that at least half a million cases of colorectal cancer occur each year worldwide. It is caused by colonic polyps, an abnormal growth of tissue that projects in due course from the lining of the intestine or rectum, into colorectal cancer. These polyps are often benign and usually

produce no symptoms. They may, however, cause painless rectal bleeding usually not apparent to the naked eye. The normal time for a polyp to reach 1 cm in diameter is five years or a little more. This 1 cm polyp will take around 5-10 years for the cancer to cause symptoms by which time it is frequently too late [11].

Diets low in fruits, less protein from vegetable sources, high age and family history are associated with increased risk of polyps. Persons smoking more than 20 cigarettes a day are 250 percent more likely to have polyps as opposed to nonsmokers who otherwise have the same risks. There is an association of cancer risk with meat, fat or protein consumption which appear to break down in the gut into cancer causing compounds called carcinogens [8]. Smoking cessation is important to decrease the likelihood of developing colon cancer. Dietary supplementation with 1500 mg of calcium or more a day is associated with a lower incidence of colon cancer. Weight reduction may be helpful in reducing the risk for colorectal cancer. Daily exercise reduces the likelihood of developing colon cancer. Turmeric, the spice which gives curry its distinctive yellow color, may also prevent colon cancer [5].

### **1.1. Hyperspectral Imaging**

Hyperspectral imaging in laboratory experiments, is a non-contact sensing technique for obtaining both spectral and spatial information about a tissue sample. Hyperspectral imaging measures a spectrum for each pixel in an image. There are many types of spectroscopy which are being used to study the spectral signatures of individual cells and underlying tissue sections. In optical spectroscopy, which measures transmission through, or reflectance from, a sample by visible or near-infrared radiation at the same wavelength as the source, classification is done mostly by statistical measures [1].

Hyperspectral images are normally produced by emission of spectra from imaging spectrometers. Spectroscopy is the study of light that is emitted by or reflected from materials and its variation in energy with wavelength [9].

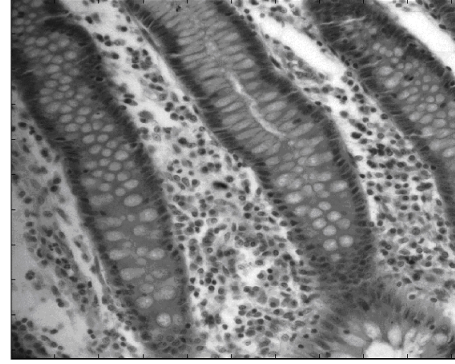
Spectrometers are used to make measurements of the light reflected from a test specimen. A prism in the centre of spectrometer splits this light into many different wavelength bands and the energy in each band is measured by detectors which are different for each band. By using large number of detectors (even a few thousand), spectrometers can make spectral measurements of bands as narrow as 0.01 micrometers over a wide wavelength range, typically at least 0.4 to 2.4 micrometers (visible through middle infrared wavelength ranges). Most approaches to analyse hyperspectral images concentrate on the spectral information in individual image cells, rather than spatial variations within individual bands or groups of bands. The statistical classification (clustering) methods often used with multispectral images can also be applied to hyperspectral images but may need to be adapted to handle high dimensionality.

Recent developments in hyperspectral imaging have enhanced the usefulness of the light microscope [3]. A standard epifluorescence microscope can be optically coupled to an imaging spectrograph, with output recorded by a CCD camera. Individual images are captured representing Y-wavelength planes, with the stage successively moved in the X direction, allowing an image cube to be constructed from the compilation of generated scan files. Hyperspectral imaging microscopy permits the capture and identification of different spectral signatures present in an optical field during a single-pass evaluation, including molecules with overlapping but distinct emission spectra. High resolution characteristics of hyperspectral imaging is reflected in two sample images in Figure 1 of colon tissue cells.

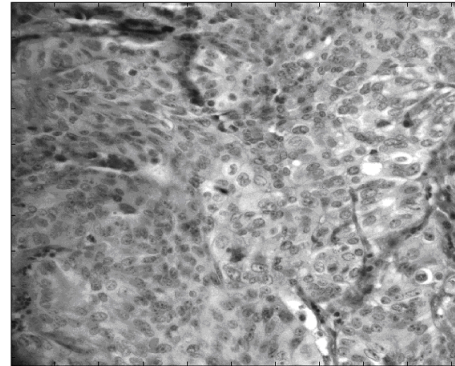
## 1.2. Related Work

A computational model of light interaction with colon tissue and classification using the tissue reflectance spectra is analyzed in [16]. Three layers: mucosa, submucosa and smooth muscle, have different reflectance properties with the light incident on their surface. Different parameters characterising the mucosa layer include blood volume fraction, haemoglobin saturation, the size of the collagen fibres, their density and the layer thickness, have unique changes for the emitted spectra of normal and malignant colon tissues. Fifty normal and seven cancerous tissues were used as an input to the system. Thus it is claimed that above model correctly predicts the spectra of colon tissue and this is in agreement with known histological changes which occur with the development of cancer which alters the macroarchitecture of the colon tissue.

Mass spectrometry, classification of samples using difference in their molecular weights, is used in [10] for the probabilistic classification of healthy vs. disease whole serum samples. The approach employs PCA followed by LDA on mass spectrometry data of complex protein mixtures. Classification is done on the principle that healthy spectrum lies



(a) Normal Cells



(b) Malignant Cells

**Fig. 1.** Colon Tissue Imagery

closer to the healthy cluster than to the disease cluster (and vice-versa). Test spectra can then be classified by minimum distance to its nearest cluster. Linear discriminant analysis creates a hyperplane that maximises the between-class variance while minimising the within-class variance.

## 2. DIMENSIONALITY REDUCTION AND SUBSPACE PROJECTION

There is a large redundant information in the subbands of hyperspectral imagery. Independent component analysis (ICA) is used to discard the redundancy and extract the variance among different wavelengths of spectra. K-means clustering is used to help the dimensionality reduction procedure and to segregate the biopsy slide into its cellular components. Classification is achieved with principal component analysis (PCA), linear discriminant analysis (LDA) and support vector machine (SVM). A brief introduction to the mathematical derivation of these methods is presented in the following subsections.

## 2.1. Independent Component Analysis (ICA)

The objective of Independent Component Analysis (ICA) is to perform a dimension reduction approach to achieve decorrelation between independent components [18]. Let us denote by  $X = (x_1, x_2, \dots, x_m)^T$  a zero-mean  $m$ -dimensional variable, and  $S = (s_1, s_2, \dots, s_n)^T$ ,  $n < m$ , is its linear transform with a constant matrix  $W$  [17]:

$$S = WX$$

Given  $X$  as observations, ICA aims to estimating  $W$  and  $S$ . The goal of ICA is to find a new variable  $S$  such that transformed components  $s_i$  are not only uncorrelated with each other, but also statistically as independent of each other as possible. An ICA algorithm consists of two parts, an objective function which measures the independence between components, entropy of each independent source or their higher order cumulants, and the second part is the optimisation method used to optimise the objective function. Higher order cumulants like kurtosis, and approximations of negentropy provide one-unit objective function. A decorrelation method is needed to prevent the objective function from converging to the same optimum for different independent components. Whitening or data sphering project the data onto its subspace as well as normalizing its variance.

## 2.2. K-Means Clustering

Clustering is the process of partitioning or grouping a given set of patterns into disjoint clusters. This is done such that patterns in the same cluster are alike and patterns belonging to two different clusters are different. The  $k$ -means method has been shown to be effective in producing good clustering results for many practical applications [2]. The aim of the  $k$ -means algorithm is to divide  $m$  points in  $n$  dimensions into  $k$  clusters so that the within-cluster sum of squared distance from the cluster centroids is minimised. The algorithm requires as input a matrix of  $m$  points in  $n$  dimensions and a matrix of  $k$  initial cluster centres in  $n$  dimensions. The number of clusters  $k$  is assumed to be fixed in  $k$ -means clustering. Let the  $k$  prototypes  $(w_1, \dots, w_k)$  be initialised to one of the  $m$  input patterns  $(i_1, \dots, i_m)$ . Therefore;

$$w_j = i_l, j \in \{1, \dots, k\}, l \in \{1, \dots, m\}$$

The appropriate choice of  $k$  is problem and domain dependent and generally a user must try several values of  $k$ . The quality of the clustering is determined by the following error function:

$$E = \sum_{j=1}^k \sum_{i_l \in C_j} |i_l - w_j|^2$$

The direct implementation of  $k$ -means method is computationally very intensive.

## 2.3. Support Vector Machine (SVM)

Support vector machine (SVM) introduces a nonlinear mapping from the input space to an implicit high-dimensional feature space, where the nonlinear and complex distributions of the patterns in the input space is linearized so that a linear separating boundary can be applied for the classification [14]. Suppose that data is mapped to some other (possibly infinite dimensional) euclidean space  $H$  using a mapping function  $\phi$ :

$$\phi : R^d \longrightarrow H^n$$

The mapping algorithm depend on the data through dot products in  $H$  in the form of  $\phi(x_i) \cdot \phi(x_j)$ . Now if there is a kernel function  $K$  which can do the required dot products than there is no need of finding the dot product themselves. This is called the kernel trick. Kernel function  $K$  should be such that;

$$K(x_i, x_j) = \phi(x_i) \cdot \phi(x_j)$$

As  $H$  is possibly infinite dimensional and  $n$  is much higher than  $d$ , so a linear separation is more straightforward. The introduction of the kernel function provides the allowance to avoid the explicit evaluation of mapping. There are several kernel functions available but polynomial, gaussian and sigmoidal kernel are used more often. The choice of kernel depends on the data and its clustering. Gaussian kernel is used in most cases because of its parameter selection [15]. It is defined as;

$$K(x_i, x_j) = e^{-\gamma(x_i - x_j)^2} + C$$

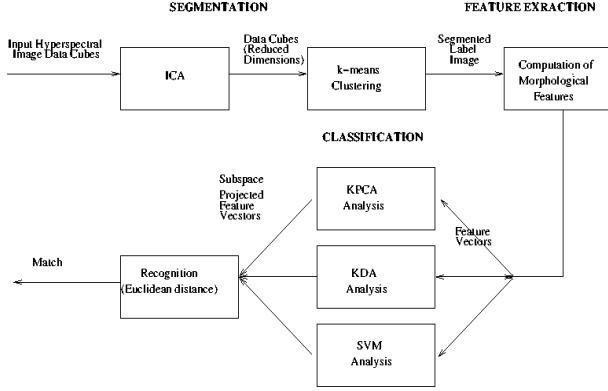
There is one common parameter  $C$  which is called constant of constraint. It is defined as the clustering of the data on the wrong side of the margin. It is constant for each data and it does not affect the tuning of the kernel. The other parameter for Gaussian kernel is the width of gaussian basis function  $\gamma$ . Its selection depends on the input data and variety of selection methods are used including grid search and newton bisection methods. Once a kernel is tuned properly, classification of test data is performed very accurately.

## 3. METHODOLOGY

The proposed classification algorithm consists of three modules as shown in Figure 2. Brief description of dimensionality reduction and feature extraction modules is given in the following sub-sections. Detailed description of the segmentation can be found in [14].

### 3.1. Segmentation

High dimensional data in the form of 3-D cubes is obtained using hyperspectral imaging. For efficient processing this



**Fig. 2.** Classification Algorithm Block Diagram

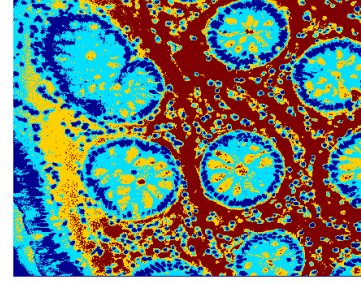
data has to be dimensionally reduced. Dimensionality reduction involves two steps, extraction of statistically independent components using Independent Component Analysis (ICA) and colour segmentation using  $k$ -means clustering. Flexible ICA (FlexICA) [6], a fixed point algorithm for ICA, adopting a generalised Gaussian density, is used for data sphering (whitening) and achieves considerable dimensionality reduction. Data is distributed towards heavy-tailedness by the high-emphasis filters. The data with reduced dimensionality is then fed to  $k$ -means clustering algorithm for segmentation.

The hyperspectral data cube containing 128 subbands is segmented into four labeled parts. Each slide of the tissue cells is divided into four regions represented by four colours as shown in Figure 3. The four labeled parts are denoted by colours as dark blue for nuclei, light blue for cytoplasm, yellow for gland secretions and red for lamina propria.

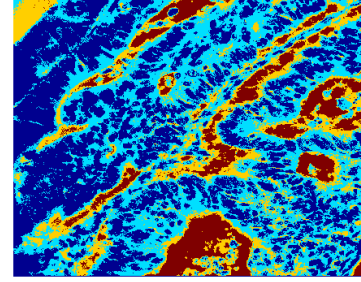
## 3.2. Feature Extraction

### 3.2.1. Morphological Features

In order for the pattern recognition process to be tractable it is necessary to represent patterns into some mathematical or analytical model. The model should convert patterns into features or measurable values, which are condensed representations of the patterns, containing only salient information [7]. Morphological features, which describe the shape, size, orientation and other geometrical attributes of the cellular components, are extracted to discriminate between two classes of input data. The segmented image is first split into four binarised image in accordance with the four cellular components. In each binary image, the corresponding cellular components i.e. nuclei, cytoplasm, gland secretions and stroma of lamina propria have binary value equal to 1.



(a) Benign Cells



(b) Malignant Cells

**Fig. 3.** Segmentation Results

### 3.2.2. Co-occurrence Features

The co-occurrence approach is based on the grey level spatial dependence. Co-occurrence matrix is computed by second-order joint conditional probability density function  $f(i, j|d, \theta)$ . Each  $f(i, j|d, \theta)$  is computed by counting all pairs of pixels separated by distance  $d$  having grey levels  $i$  and  $j$ , in the given direction  $\theta$ . The angular displacement  $\theta$  usually takes on the range of values from  $\theta = 0, 45, 90, 135$  degrees. The co-occurrence matrix captures a significant amount of textural information. The diagonal values for a coarse texture are high while for a fine texture these diagonal values are scattered. To obtain rotation invariant features the co-occurrence matrices obtained from the different directions are accumulated. The three set of attributes used in our experiments are Energy, Inertia and Local Homogeneity.

$$E = \sum_i \sum_j [f(i, j|d, \theta)]^2$$

$$I = \sum_i \sum_j [(i - j)^2 f(i, j|d, \theta)]$$

$$LH = \sum_i \sum_j \frac{f(i, j|d, \theta)}{1 + (i + j)^2}$$

## 4. EXPERIMENTS

### 4.1. Experimental Setup

The experimental setup consists of a CRI Nuance microscope and a CCD camera. Two different datasets are prepared. Each dataset contains ten biopsy images of the colon biopsies on a tissue micro-array. These samples come from different patients and are prepared by *H&E* staining. Each slide is illuminated with a tuned light source (capable of emitting any combination of light frequencies in the range of 450-850 nm), followed by magnification to 400 X. Thus several images, each image using a different combination of light frequencies, are produced [4]. Dataset I contains ten biopsy slides with 32 hyperspectral bands and each slide has a 1024x1024 resolution. 128 hyperspectral bands are used in dataset II with 491x652 resolution for each band.

The first set of experiments is carried out with morphological feature extraction method. Each image is divided into  $64 \times 64$  blocks or patches. Morphological operation is performed on the patches for extraction of feature vectors using different combinations of ten scalar morphological properties. The testing is done on the format of leave one out (LOO) and blocks from nine slides make training set while blocks from the tenth slide is used for testing. Euler number, area, extent, convex area, equivalent diameter and other elliptical parameters are calculated for each block. Using ten parameters for each binary image, a feature vector containing 40 dimensions represents each block. PCA with twenty principal components is employed in the first experiment. Supervision in the training set is introduced through LDA in the second experiment. Third experiment uses SVM with gaussian kernel. Its tuning is done with newton bisection method which gives it sufficient bandwidth to achieve a reasonable classification accuracy.

### 4.2. Experiments with Co-occurrence Features

The second set of experiments uses directional textural attributes which are extracted for each block. Dataset II is used because it has less resolution as compared to dataset I. Co-occurrence matrix is computed for the block size of  $64 \times 64$  for each slide. Three co-occurrence features, containing angular second moment (Energy), variance and homogeneity, are calculated while pixel distance is varied from one pixel to two pixel values. Four directional features in the direction of 0, 45, 90 and 135 are concatenated together so that a feature vector with 24 dimensions is used in the classifiers. PCA and LDA are used in first two experiments. The last experiment is carried out with SVMs. Gaussian kernel with grid search tuning method is used with constant of constraint having very small value.

### 4.3. Results

Classification Accuracy (%)				
Biopsy No.	Block Size	PCA	LDA	SVM
B1	64x64	64.55	68.57	68.57
B2	64x64	53.66	56.76	78.57
B3	64x64	55.88	54.36	75.71
B4	64x64	53.64	54.36	77.14
B5	64x64	57.93	59.64	64.29
M1	64x64	41.55	45.22	75.71
M2	64x64	47.75	49.26	62.86
M3	64x64	61.91	61.95	74.29
M4	64x64	51.54	52.63	75.71
M5	64x64	53.54	55.29	78.57

Table 1. Morphological Features

The classification accuracy in the morphological set of experiments is about 80 percent with PCA and LDA. Eight slides on the whole are classified correctly with a threshold of 50 percent on the patches. SVM gives an accuracy of 90 percent with 9 slides out of ten are being classified in the true classes. With directional textural features, blocks classification accuracy increases for each slide in comparison to first set of experiments. Overall slide accuracy is upto 90 percent. SVM again outperforms PCA and LDA. One way of explanation can be such that SVM introduces a nonlinear mapping from the input space which make classification of nonlinear boundary patterns similar to linear boundary problems.

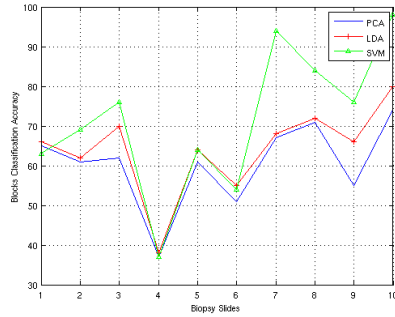
## 5. CONCLUSIONS

In this paper, classification of colon tissue cells is achieved using the morphology of the glandular cells of the tissue re-

Classification Accuracy (%)				
Biopsy No.	Block Size	PCA	LDA	SVM
B1	64x64	65.71	66.20	62.86
B2	64x64	61.43	62.86	68.57
B3	64x64	62.86	70.29	75.71
B4	64x64	37.14	38.57	37.14
B5	64x64	61.43	64.29	64.29
M1	64x64	51.43	55.71	54.29
M2	64x64	67.14	68.86	94.29
M3	64x64	71.43	72.86	84.29
M4	64x64	55.71	66.20	75.71
M5	64x64	74.29	80.71	98.57

Table 2. Co-occurrence Features





Co-occurrence Features Classification

**Fig. 4.** Blocks Classification Accuracy

gion. There is an indication that the morphology of the cells, obtained from the hyperspectral analysis of biopsy slides, has strong discriminatory power. Regular structured cell shapes with fine orientation of the tissue glands are characteristics of normal cells, whereas irregular and deformed glandular shapes represent malignant tissue. In morphological analysis, five features' subset achieves accuracy upto 90 percent on whole biopsy images. In the second set of experiments with gray level co-occurrence matrix and using a feature vector of 24 dimensions, reasonable classification is performed even with simple classifiers like LDA. However, employing properly tuned Gaussian kernel with grid search method, accuracy, even for individual blocks, is quite good.

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